

AIAG-VDA FMEA 표준제정(1st Edition) 대응전략



The background of the slide is a close-up photograph of vibrant green leaves, some with water droplets, set against a soft, out-of-focus background of more greenery.

- 목 차 -

1. AIAG_VDA FMEA Introduction

2. SW를 활용한 New FMEA 대응

AIAG-VDA FAILURE MODE AND EFFECTS ANALYSIS (FMEA) Handbook First Edition

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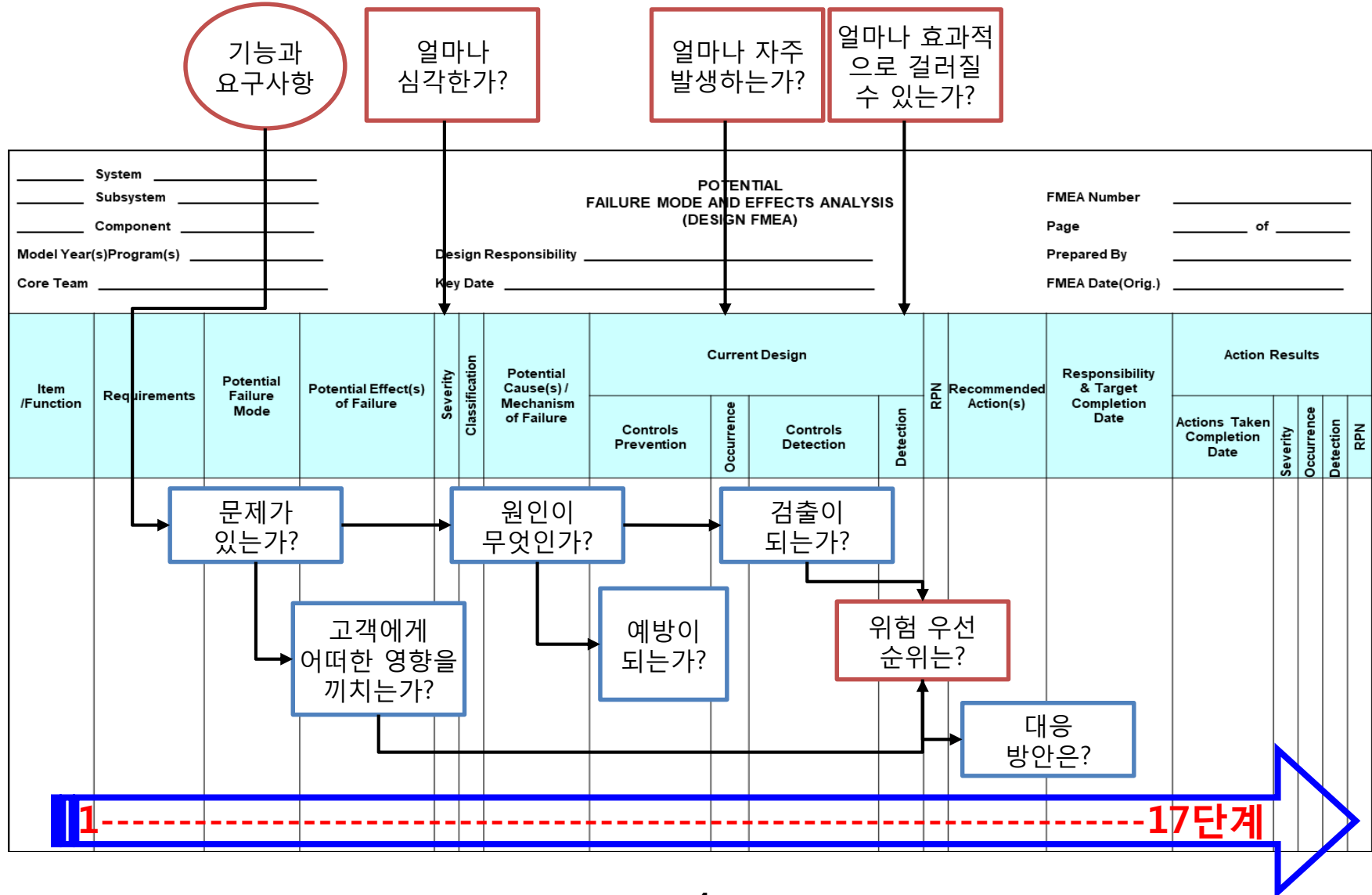
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1. 현재 AIAG-FMEA(4th : 2008)



1. 현재 VDA-FMEA(2th : 2012)

The Five Steps for the Preparation of the FMEA

System Analysis

Risk Analysis and Actions

1st Step

2nd Step

3rd Step

4th Step

5th Step

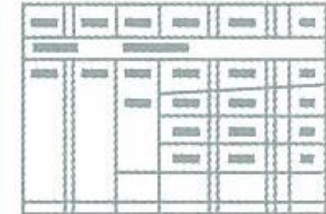
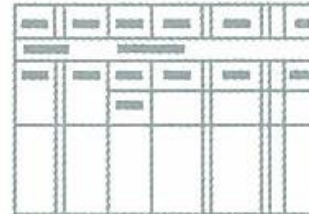
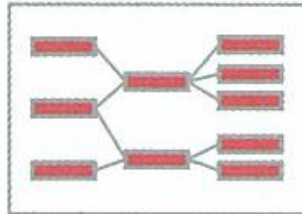
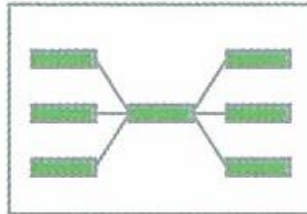
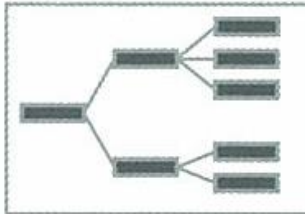
Structure Analysis

Function Analysis

Failure Analysis

Actions Analysis

Optimization



- Record and structure the involved elements
- Create system structure

- Assign functions to the structure elements
- Link functions

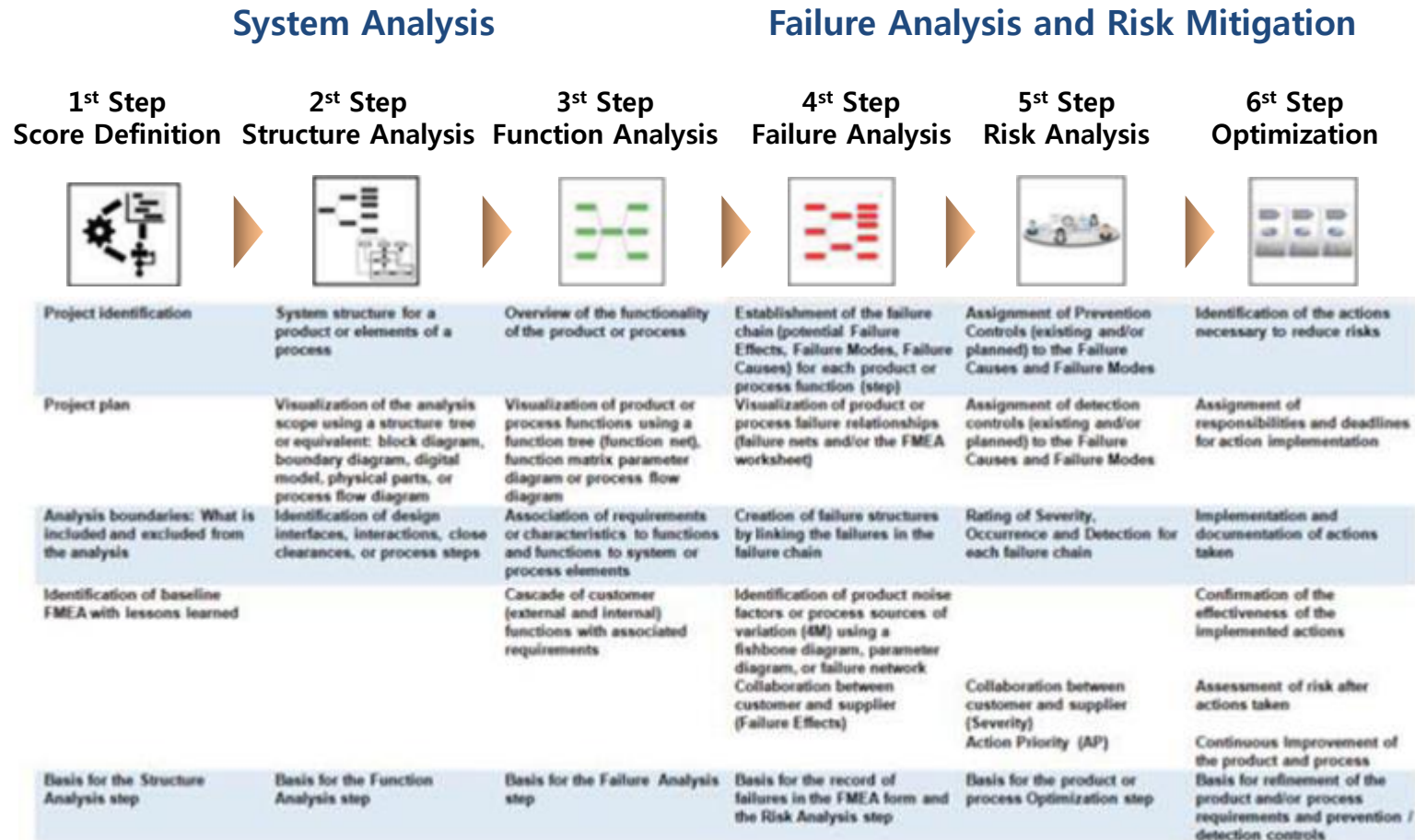
- Assign failures to the functions
- Link failures

- Document current avoidance and detection actions
- Evaluate current status

- Reduce risk with additional actions
- Evaluate changed status

2. New FMEA 전개방법

DFMEA는 6단계로 구성되어 있고 FMEA를 수행하기 위해서 6단계를 체계적으로 접근하고 기술적 위험 분석 기록을 알 수 있음.



2. New FMEA 전개방법

[DFMEA Spreadsheet Failure Structure]

STRUCTURE ANALYSIS(STEP2)			FUNCTION ANALYSIS(STEP3)			FAILURE ANALYSIS(STEP4)			
1. Next Higher Level	2. Focus Element	3. Next Lower Level or Characteristic Type(Geometry, Material, Coating, etc)	1. Next Higher Level Function and Requirement	2. Focus Element Function and Requirement	3. Next Lower Level Function and Requirement or Characteristic	1. Failure Effects(FE) to the Next Higher Level Element and or Vehicle user	Severity(S) of FE	2. Failure Mode(FM) of the Focus Element	3. Failure Cause(FC) of the Next Lower Element or Characteristic
Window Lifter Motor	Electrical Motor	Brush Card Base Body	Convert electrical energy into mechanical energy(acc..control signal)	Commutation system transports the electrical current between coil pairs of the electro magnetic converter	Brush card body transports forces between spring and motor body to hold the brush spring system x, y, z position(support commutating contact point)	Torque and rotating velocity of the window lifter motor too low	6	Commutation system intermittently connects the wrong coils(L1, 3 and 2 instead of L1, 2 and 3), resulting in angle deviation	Brush card body bends in contact area of the carbon brush, due to too low stiffness in carbon brush contact area

2. New FMEA 전개방법

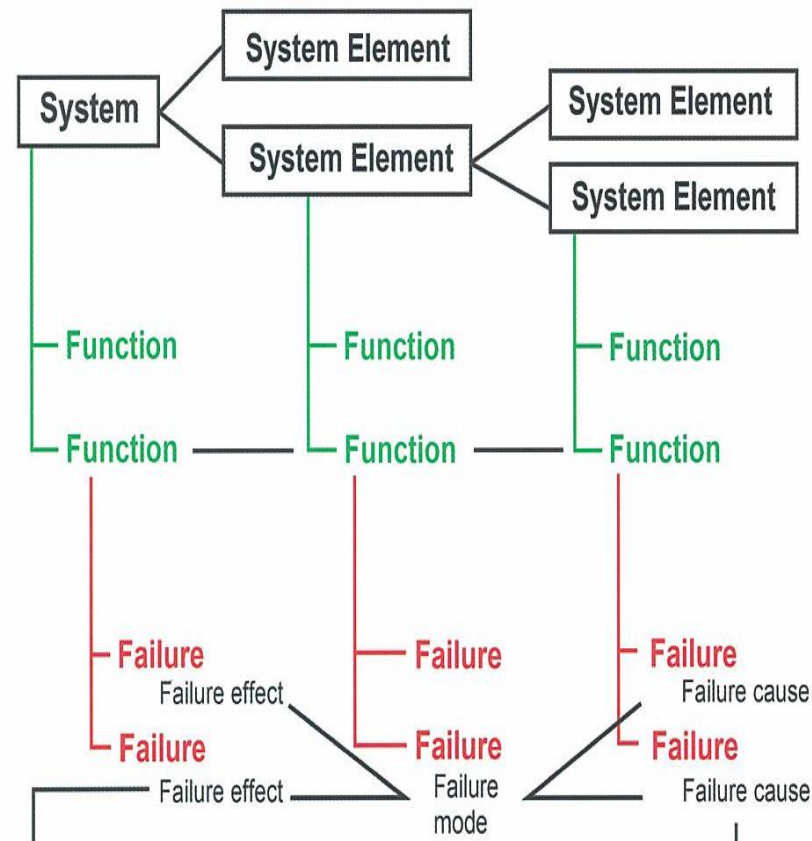
[DFMEA Spreadsheet Failure Structure]

STRUCTURE ANALYSIS(STEP2)			
1. Next Higher Level	2. Focus Element	3. Next Lower Level or Characteristic Type(Geometry, Material, Coating, etc)	
Window Lifter Motor	Electrical Motor	Brush Card Base Body	
FUNCTION ANALYSIS(STEP3)			
1. Next Higher Level Function and Requirement	2. Focus Element Function and Requirement	3. Next Lower Level Function and Requirement or Characteristic	
Convert electrical energy into mechanical energy(acc. control signal)	Commutation system transports the electrical current between coil pairs of the	Brush card body transports forces between spring and motor body to hold the brush spring	
FAILURE ANALYSIS(STEP4)			
1. Failure Effects(FE) to the Next Higher Level Element and or Vehicle user	Severity(S) of FE	2. Failure Mode(FM) of the Focus Element	3. Failure Cause(FC) of the Next Lower Element or Characteristic
Torque and rotating velocity of the window lifter motor too low	6	Commutation system intermittently connects the wrong coils(L1, 3 and 2 instead of L1, 2 and 3), resulting in angle deviation	Brush card body bends in contact area of the carbon brush, due to too low stiffness in carbon brush contact area

Structural Analysis

Functional Analysis

Failure Analysis



2.1 Design FMEA 1st Step: Scope Definition

Design Failure Mode and Effects Analysis(DESIGN FMEA)

SCOPE DEFINITION(STEP1)

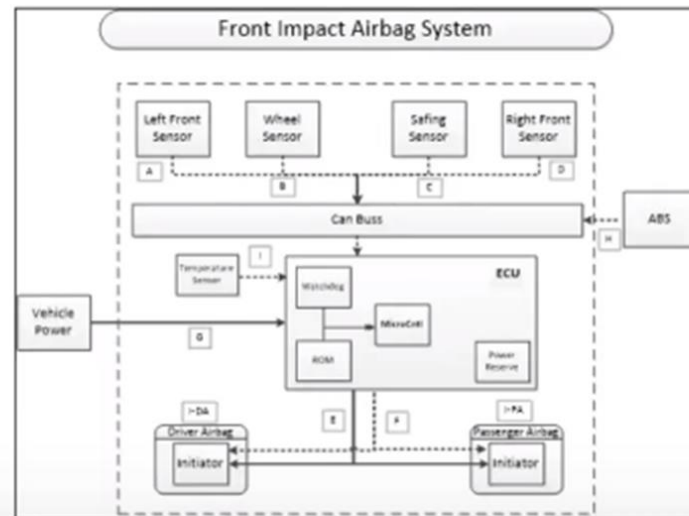
Company Name :	Name of Company responsible for DFMEA	Subject :	Name of DEMA project	DFMEA ID Number :	Determined by company
Engineering Location :	Geographical location	DFMEA Start Date :	Date DFMEA project started	Design Responsibility :	Name of DFMEA owner
Customer Name :	Name of customer(s) or [Product Family]	DFMEA Revision Date :	Latest revision date	el :	[Business Use, Confidential, Proprietary, etc..]



1st Step: Scope Investigation

5Ts

- FMEA Team
 - Who needs to be on the team?
- FMEA Timing
 - When is this due?
- FMEA Intent
 - Why are we here?
- FMEA Task
 - What work needs to be done?
- FMEA Tool
 - How to conduct analysis?



2.2 Design FMEA 2st Step: Structure Analysis

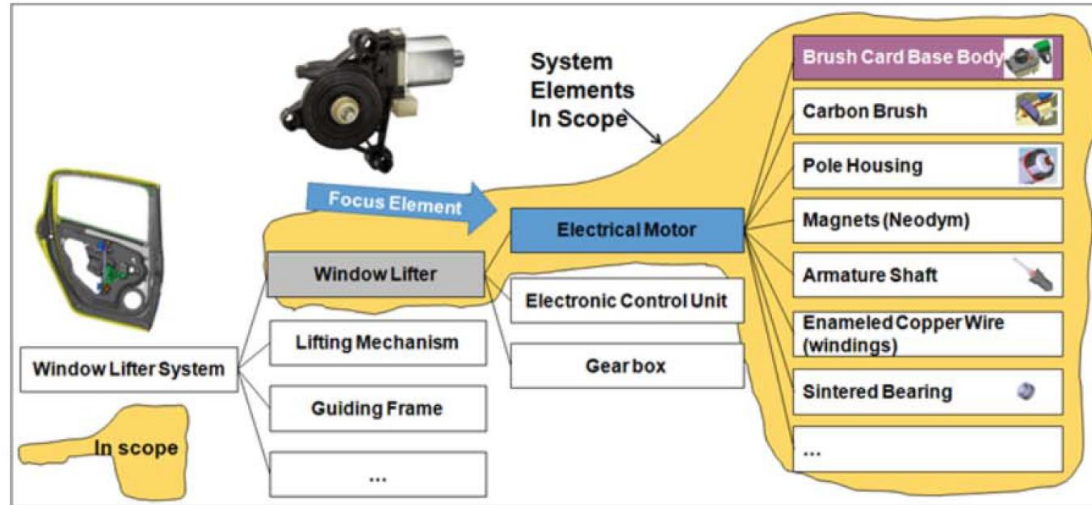
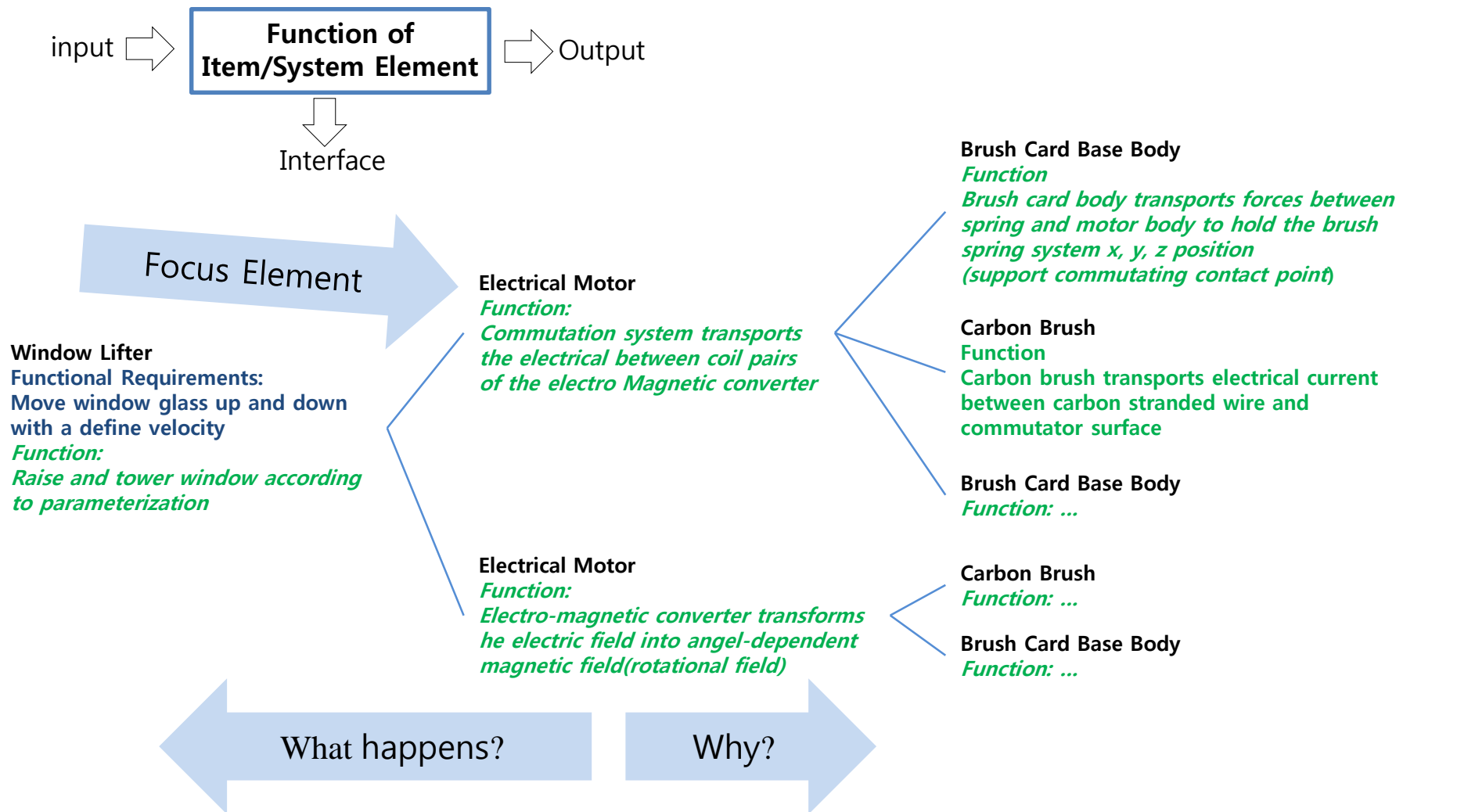


Figure 2.2-2 Example of Structure Analysis using a Structure Tree

STRUCTURE ANALYSIS(STEP2)		
1. Next Higher Level	2. Focus Element	3. Next Lower Level or Characteristic Type(Geometry, Material, Coating, etc)
Window Lifter	Electrical Motor	Brush Card Base Body

2.3 Design FMEA 3st Step: Function Analysis



[Example of Function Analysis using a Structure Tree]

2.4 Design FMEA 4st Step: Failure Analysis (1/4)

FAILURE ANALYSIS

Visualization of the Failure Analysis

FAILURE ANALYSIS(STEP4)			
1. Failure Effects(FE) to the Next Higher Level Element and or Vehicle user	Severity (S) of FE	2. Failure Mode(FM) of the Focus Element	3. Failure Cause(FC) of the Next Lower Element or Characteristic
FMEA Form, Failure Net			

2.4 Design FMEA 4th Step: Failure Analysis (2/4)

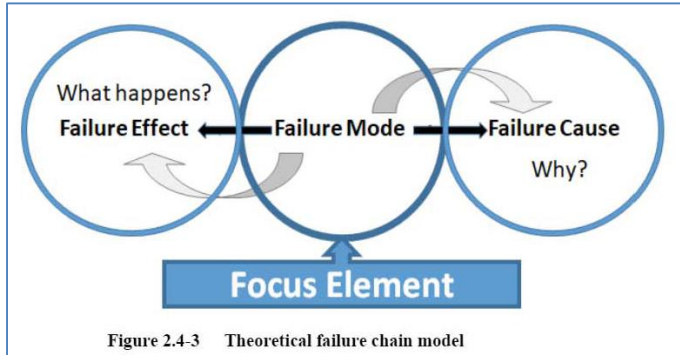
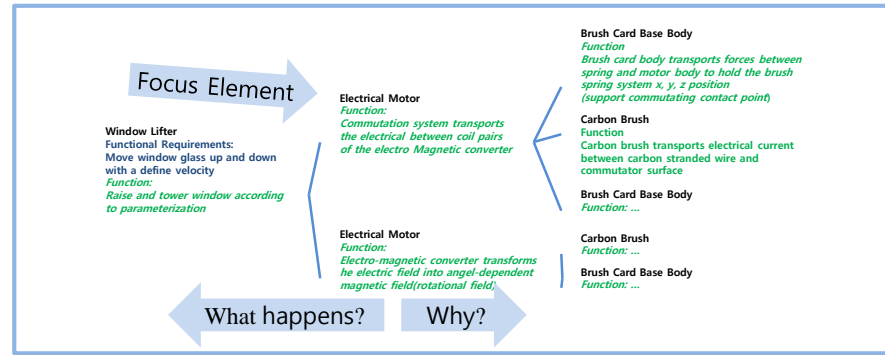


Figure 2.4-3 Theoretical failure chain model

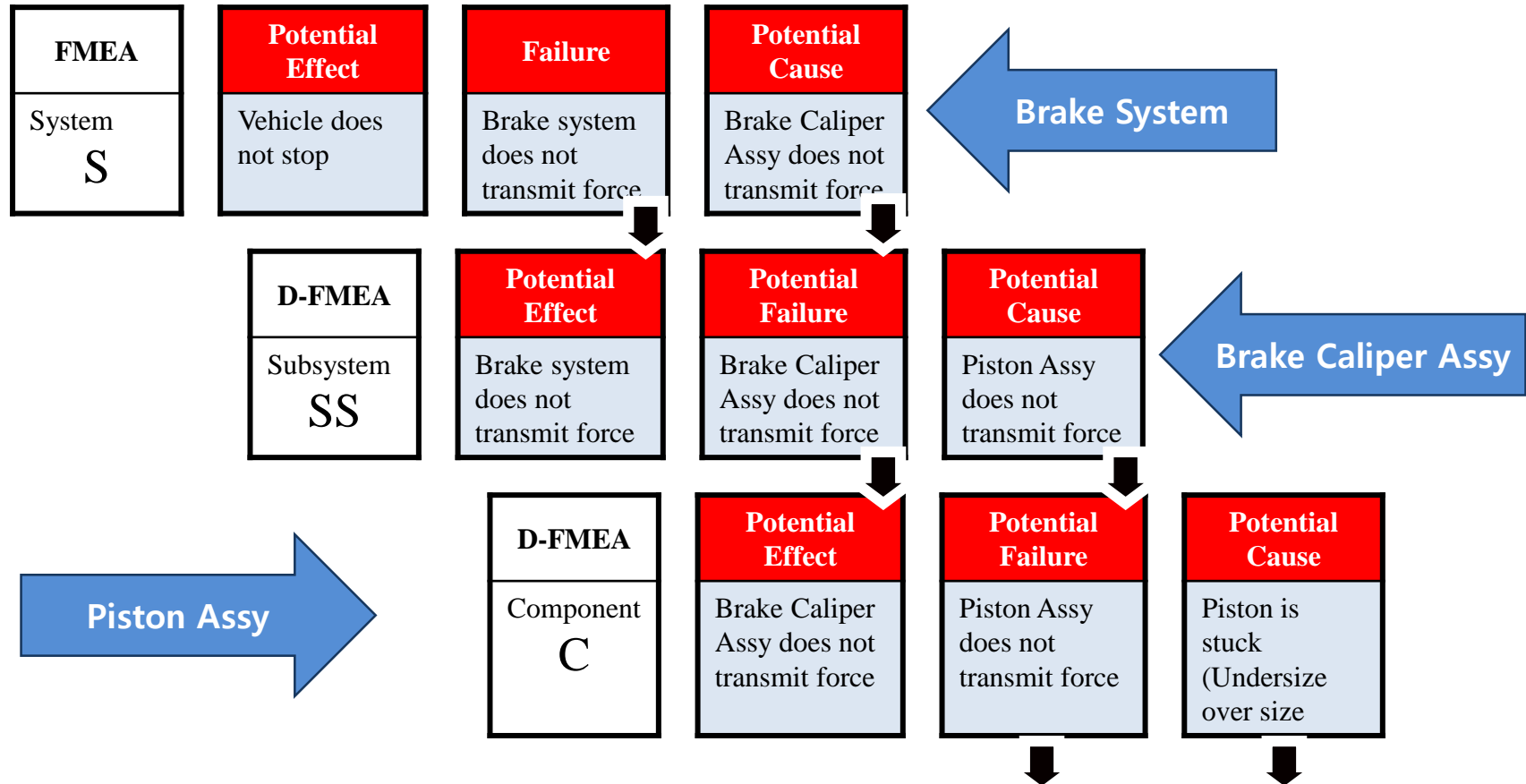


DFMEA interfaces					
Analysis Level	FMEA at Level 1	FMEA at Level 2	FMEA at Level 3	Element (Item/Station)	Failures
Product	FE			Window Lifter System	Window lifting speed to low
System element	FM	FE		Window Lifter	Torque and rotating velocity of the window lifter motor too low
Sub-System Element	FC	FM	FE	Electrical Motor	Commutation system intermittently connects the wrong coils (L1, 3 and 2 instead of L1,2 and 3)
Component Element		FC	FM	Brush Card Base Body	Carbon brush transports too little current due to high resistance to the commutator surface
(Design) Feature characteristic			FC	Distance brush to commutator	

[Failure Structure at different levels]

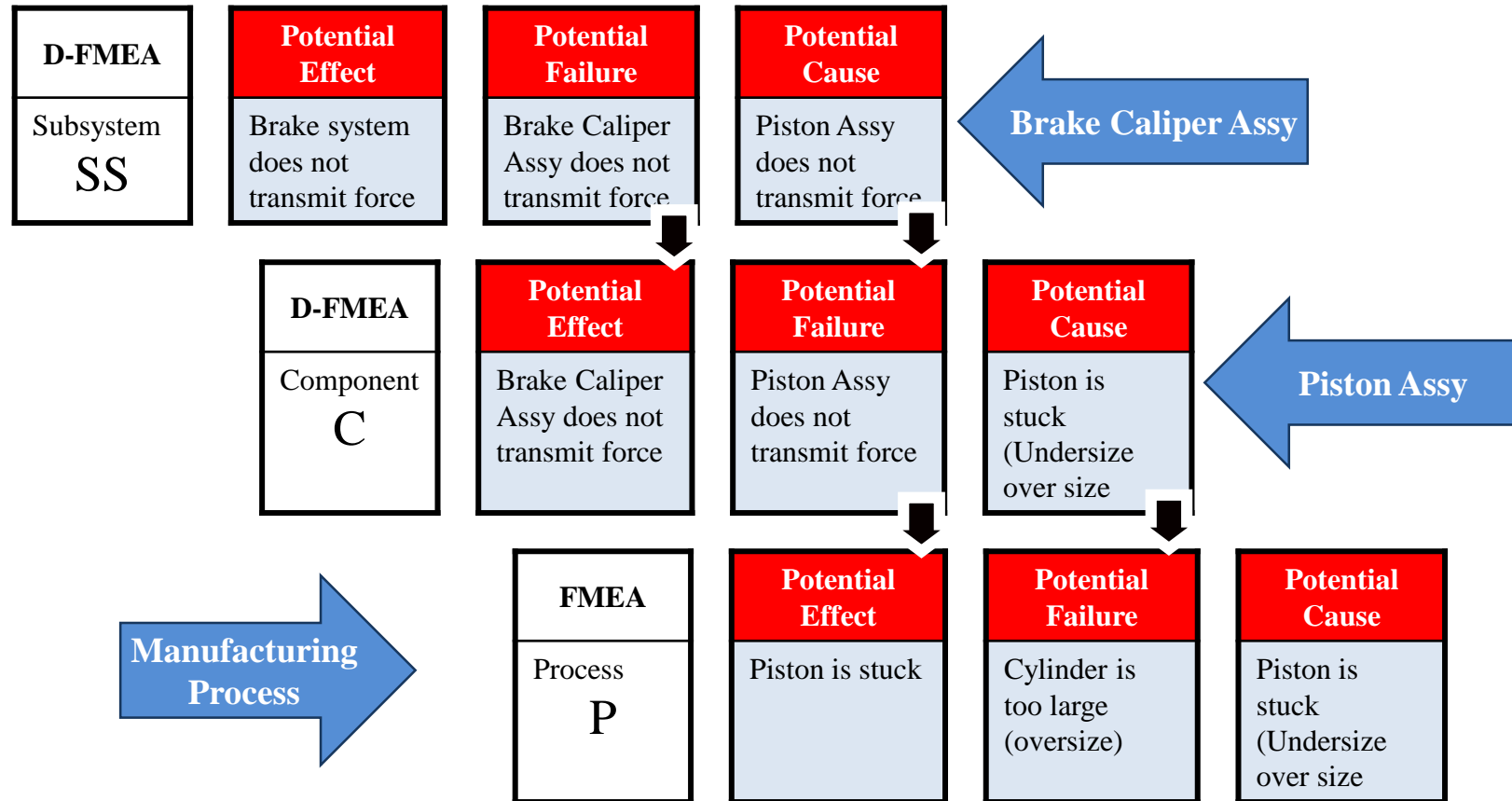
2.4 Design FMEA 4st Step: Failure Analysis (3/4)

FMEA Failure Analysis : Relationships



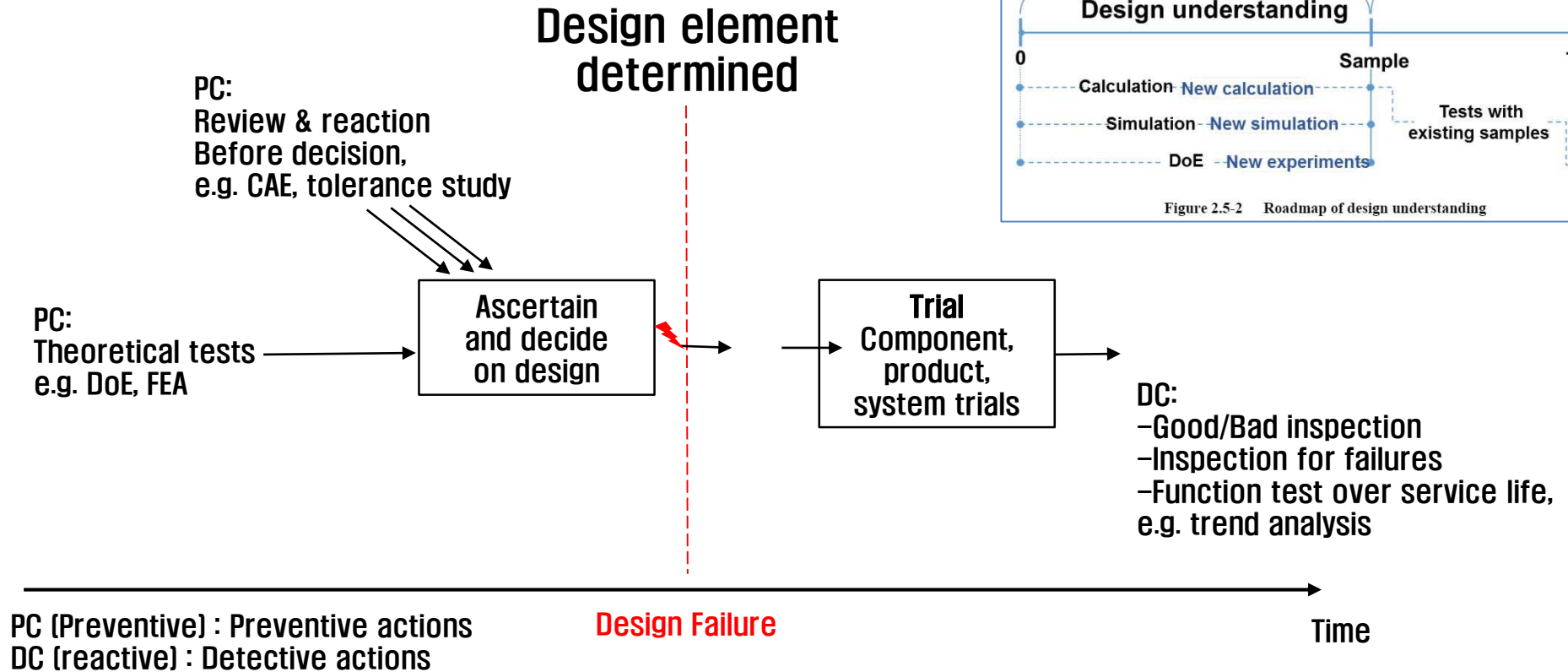
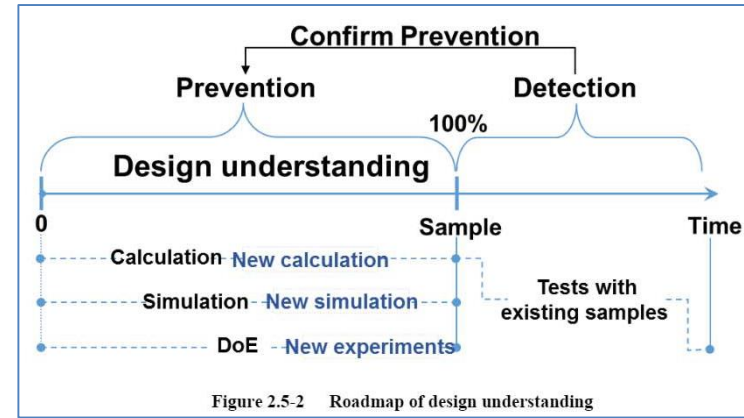
2.4 Design FMEA 4st Step: Failure Analysis (4/4)

FMEA Failure Analysis : Relationships



2.5 Design FMEA 5th Step: Risk Analysis

[Prevention and Detection in the Design FMEA]



2.5 Design FMEA 5st Step: Risk Analysis > 평가기준

Product General Evaluation Criteria Severity S			
Potential Failure Effects rated according to what the End User might experience		Blank until filled	
SEV	S	Occurrence Potential O for the Product Design	
		10	Affects safe operation of other vehicles or passenger(s) or
9	Noncompliance	OCC	Estimated Occurrence Occurrence during in-tended service life cannot be determined at this time, no preventive controls, or occurrence during intended service life of the item is
8	Loss of essential function for normal driving life.		

Table D3 DFMEA DETECTION			
Detection Potential D for the Validation of the Product Design			
Detection Controls rated for each detection activity performed prior to delivery of the design for production. The timing of the detection control (before or after technical release) should also be considered as part of the detection rating.			
DET	Ability to Detect	Detection Criteria	Corporate or Product Line Examples
10	Absolute uncertainty	No test or test procedure.	
9	Very remote	Test procedure not designed to specifically detect the cause and/or failure mode.	
8	Remote	Ability of detection control to detect the failure cause or failure mode is remote based on verification or validation procedure, sample size, mission profile, etc.	
7	Very Low	Ability of detection control to detect the failure cause or failure mode is very low based on verification or validation procedure, sample size, mission profile, etc.	

2.5 Design FMEA 5st Step: Risk Analysis > Risk Action (1)

Priority High (H): Highest priority for action.
The team **must** either identify an appropriate action to improve prevention and / or detection controls or justify and document why current controls are adequate.

Priority Medium (M): Medium priority for action.
The team **should** identify appropriate actions to improve prevention and / or detection controls, or, at the discretion of the company, justify and document why controls are adequate.

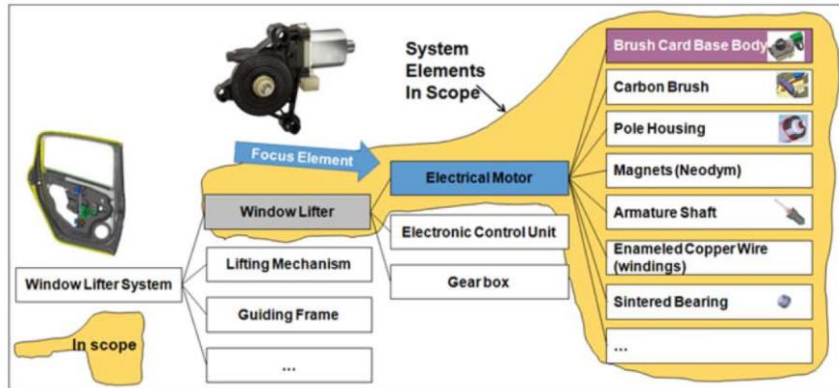
Priority: Low (L) Low priority for action.
The team **could** identify actions to improve prevention or detection controls.

2.5 Design FMEA 5th Step: Risk Analysis > Risk Action (2)

S	O	D	AP	DFMEA Action Priority Logic
9-10	6-10	1-10	H	High priority due to safety and/or regulatory effects that have a high or very high occurrence rating
9-10	4-5	7-10	H	High priority due to safety and/or regulatory effects that have a moderate occurrence rating and high detection rating
9-10	4-5	5-6	H	High priority due to safety and/or regulatory effects that have a moderate occurrence rating and moderate detection rating
9-10	4-5	1-4	M	Medium priority due to safety and/or regulatory effects that have a moderate occurrence rating and low detection rating
9-10	1-3	7-10	H	High priority due to safety and/or regulatory effects that have a low occurrence and high detection rating
9-10	1-3	5-6	M	Medium priority due to safety and/or regulatory effects that have a low occurrence rating and moderate detection rating
9-10	1-3	1-4	L	Low priority due to safety and/or regulatory effects that have a low occurrence and low detection rating
5-8	8-10	2-10	H	High priority due to the loss or degradation of an essential or convenience vehicle function that has a very high occurrence rating
5-8	6-7	7-10	H	High priority due to the loss or degradation of an essential or convenience vehicle function that has high occurrence and high detection rating
5-8	6-7	5-6	H	High priority due to the loss or degradation of an essential or convenience vehicle function that has high occurrence and moderate detection rating
5-8	6-7	1-4	M	Medium priority due to the loss or degradation of an essential or convenience vehicle function that has a high occurrence and low detection rating
5-8	4-5	7-10	H	High priority due to the loss or degradation of an essential or convenience vehicle function that has a moderate occurrence rating and high detection rating
5-8	4-5	5-6	H	High priority due to the loss or degradation of an essential or convenience vehicle function that has a moderate occurrence rating and moderate detection rating
5-8	4-5	1-4	M	Medium priority due to the loss or degradation of an essential or convenience vehicle function that has a moderate occurrence and low detection rating
5-8	1-3	7-10	M	Medium priority due to the loss or degradation of an essential or convenience vehicle function that has a low occurrence and high detection rating
5-8	1-3	5-6	M	Medium priority due to the loss or degradation of an essential or convenience vehicle function that has a low occurrence and moderate detection rating

2.5 New Design FMEA Summary

① Scope Definition



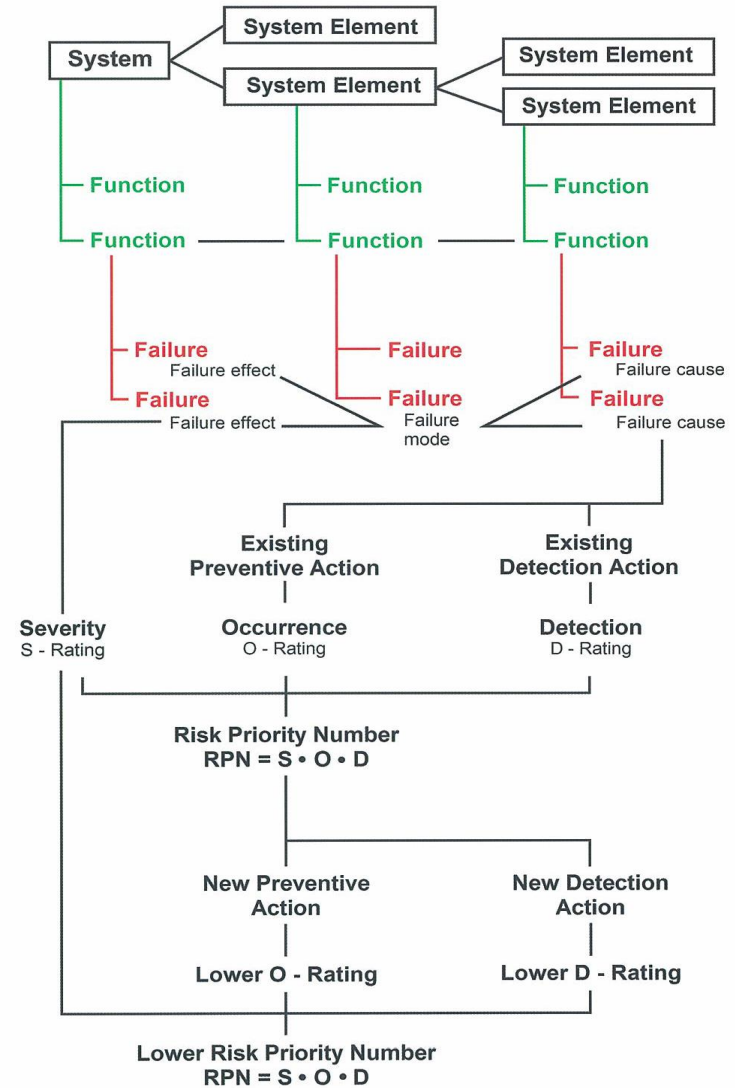
② Structural Analysis

③ Functional Analysis

④ Failure Analysis

⑤ Actions Analysis

⑥ Optimization

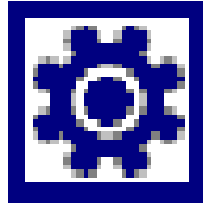


2.5 Design FMEA 5th Step: Risk Analysis > Action Priority(AP)

1.6.4 FMEA Tools


There are numerous FMEA software packages that can be used to develop a DFMEA and PFMEA as well as follow up on actions. This software ranges from dedicated FMEA software to standard spreadsheets customized to develop the FMEA. Companies may develop their own in-house database solution or purchase commercial software. In any case, the FMEA team must have knowledge of how to use the FMEA software for their project as required by the company and/or customer.

- 시중에는 조치분석으로 DFMEA와 PFMEA를 발전시킬 수 있는 다양한 FMEA 소프트웨어 패키지는 많습니다.
- 그 범위(다양성)는 FMEA 전용 소프트웨어에서 FMEA 개발을 위한 개별 맞춤형 된 표준 스프레드시트 등 다양합니다.
- 회사는 자체 데이터베이스 솔루션을 개발하거나 상용 소프트웨어를 구매할 수 있습니다.
- 어떠한 경우에도 FMEA 팀은 회사 및 고객이 요구하는 대로 프로젝트 별로 FMEA 소프트웨어의 사용 방법을 알고 있어야 합니다.

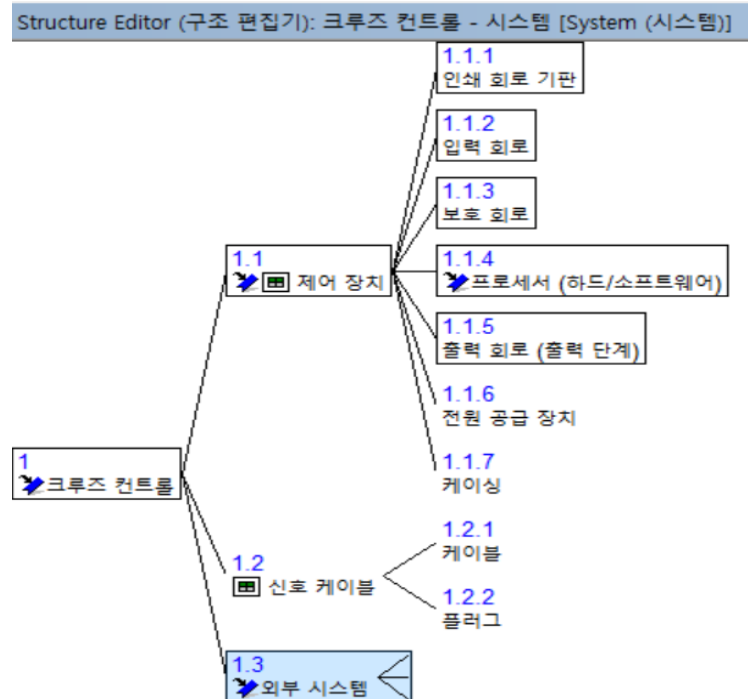


IQ FMEA

1단계 : Scope Definition

	Design F M E A	Number (번호): 1.1
	크루즈 컨트롤 System	Page (페이지):
System (시스템): X Subsystem (하위 ...X) Component (구성 ...X)	Design responsibility (설계 책임): 박창도	Prepared by (준비한 사람): 홍영희, 김원영
Item (아이템): 크루즈 컨트롤 - 시스템	Completion date (완료 날짜): 2018.09.13	Created (생성됨): 2018-09-01 Modified (수정됨): 2018-09-09
Model year(s)/vehicle(s) (모델 연도(들)/자동차(들)): 제어 장치		
Team (팀): 솔루션 팀		

2단계 : Structure Analysis



3단계 : Function Analysis

The screenshot displays the Function Net Editor interface. On the left, a hierarchical tree shows the function structure: '1 크루즈 컨트롤' (Cruise Control) branches into '1.1 신호 케이블' (Signal Cable) and '1.2 제어 장치' (Control Unit). '1.1 신호 케이블' further branches into '1.1.1 케이블' (Cable) and '1.1.2 플러그' (Plug). '1.2 제어 장치' branches into '1.3.1 / 센서1' (Sensor 1). The right pane shows a detailed view of function '1.1 신호 케이블 {1}', listing sub-functions 1.1.a through 1.1.g. A red box highlights the top-level function icon, and a blue arrow points to it from a text box at the bottom.

상위 하위 기능이 연결된 상태 표시

기능 네트워크 편집기 (Function Net Editor): 크루즈 컨트롤 - 시스템 [시스템 (System)]	상위 하위 기능이 연결된 상태 표시						
<table border="1"> <tr> <td>크루즈 컨트롤</td> <td>신호 케이블</td> <td>케이블</td> </tr> <tr> <td>사양에 따라 추진을 통제한다.</td> <td>신호를 수신기에서 제어 장치로 손실없이 전달한다.</td> <td>명시된 조정 신호를 전송한다.</td> </tr> </table>	크루즈 컨트롤	신호 케이블	케이블	사양에 따라 추진을 통제한다.	신호를 수신기에서 제어 장치로 손실없이 전달한다.	명시된 조정 신호를 전송한다.	
크루즈 컨트롤	신호 케이블	케이블					
사양에 따라 추진을 통제한다.	신호를 수신기에서 제어 장치로 손실없이 전달한다.	명시된 조정 신호를 전송한다.					

4단계 : 고장 분석

The screenshot displays the Failure Net Editor interface for '크루즈 컨트롤 - 시스템 [시스템 (System)]'. On the left, a hierarchical tree shows the system structure: '1 크루즈 컨트롤' branches into '1.1 신호 케이블', '1.2 제어 장치', and '1.3 외부 시스템'. '1.1 신호 케이블' further branches into '케이블' and '1.1.2 플러그'. '1.2 제어 장치' branches into '1.3.1 센서1', '1.3.2 센서2', and '1.3.3'. The right pane lists failure modes with icons: 1.1.a (green), 1.1.a.1 (red), 1.1.a.2 (red), 1.1.b (green), 1.1.c (green), 1.1.d (green), 1.1.d.1 (red), 1.1.e (green), 1.1.e.1 (red), 1.1.f (green), and 1.1.f.1 (red). A red box highlights the icon for 1.1.a.1, and a blue box highlights the text '상위 하위 고장이 연결된 상태 표시'.

고장 네트워크 편집기 (Failure Net Editor): 크루즈 컨트롤 - 시스템 [시스템 (System)]

크루즈 컨트롤	신호 케이블	케이블
운전이 통제 되지 않는다.	신호가 없다.	전도체를 물리적, 화학적 영향으로부터 보호하지 않는다.

4단계 : 고장 분석

- 크루즈 컨트롤 {1}
 - 사양에 따라 추진을 통제한다. {1}
 - ☹ 운전 통제가 사양을 벗어난다. {1}
 - ☹ 운전이 통제 되지 않는다. {1}
 - ☹ 수명 기간동안 기능을 상실한다. {1}
 - ☹ 크루즈 컨트롤의 고장 {1}
- 위험 상황에서 긴급 자단이 가능하다. {1}
- 작동 상태 신호를 보낸다. {1}
- 법적 요구사항을 충족한다. {1}
- 고객의 조립 요구사항을 준수한다. {1}
- 신호 케이블 {1}
 - 신호를 수신기에서 제어 장치로 손실없이 전달한다. {1}
 - ☹ 신호가 없다. {1}
 - ☹ 신호가 정확한 입력값을 나타내지 않는다. {1}
 - 신호를 센서에서 제어 장치로 손실없이 전달한다. {1}
 - 신호를 제어 장치에서 속도 제어 장치로 손실없이 전달한다. {1}
 - 환경 조건을 견딘다. {1}
 - 전자기 방사선에 대한 사양을 만족한다. {1}
 - 수동 조립이 가능하다. {1}
 - 여러번 교환이 가능하다. {1}
- 플러그 {1}
 - 케이블과 플러그 사이의 기계적 인터페이스를 가진다. {1}
 - 케이블과 플러그 사이의 전기적 인터페이스를 가진다. {1}
 - ☹ 케이블과 플러그 사이에 전기 연결이 안 되거나 안전하지 않게 연결된다. {1}
 - ☹ 케이블과 플러그 사이의 인터페이스를 통한 신호 왜곡 {1}
 - ☹ 케이블과 플러그 사이의 인터페이스를 통한 신호 레벨의 손실 {1}
 - ☹ 수명 기간에 납땜 연결이 깨진다. {1}



양식 에디터 AIAG (4쇄, D) (FMEA Forms Editor AIAG (4th edition, D)): 신호 케이블 (크루즈 컨트롤)

기능 (Function)	요구 (Requirement)	가능 오류 (Potential failure)	오류의 가능한 효과(들) (Potential effect(s) of failure)	S (S)	C (C)	오류의 가능한 원인(들) (Potential cause(s) of failure)	현재 예방 조치 (Current preventive action)
신호를 수신기에 제어 장치로 손실없이 전달한다		1.2.a.1 ☹ 신호가 없다.	[크루즈 컨트롤] 1.a.2 ☹ 운전이 통제 되지 않는다.			[플러그] 1.2.2.b.1 ☹ 케이블과 플러그 사이에 전기 연결이 안 되거나 안전하지 않게 연결된다.	

5단계 : Risk Analysis

구조 편집기 (Structure Editor): 크루즈 컨트롤 - 시스템 [시스템 (System)]

FMEA 양식 편집기 AIAG (4 판, D) (FMEA Forms Editor AIAG (4th edition, D)): 신호 케이블 (크루즈 컨트롤 - 시스템 [시스템 (System)])

기능 (Function)	요구사항 (Requirement)	잠재적 고장 (Potential failure)	고장의 잠재적 영향(들) (Potential effect(s) of failure)	S (S)	C (C)	고장의 잠재적 원인(들) (Potential cause(s) of failure)	현재 예방 조치 (Current preventive action)	O (O)	현재 검출 조치 (Current detection action)	D (D)	RPN (RPN)
신호를 수신기에서 제어 장치로 손실없이 전달한다.		1.1.a.2 신호가 정확한 입력값을 나타내지 않는다.	{1 크루즈 컨트롤 - 시스템} [크루즈 컨트롤] 1.a.1 운전 통제가 사양을 벗어난다.	9		{1 크루즈 컨트롤 - 시스템} [케이블] 1.1.1.a.1 주어진 실행 조건에서 전송시 신호 조정이 바뀐다. {1 크루즈 컨트롤 - 시스템} [케이블] 1.1.1.c.1 환경으로부터 전기적으로 전도체를 격리시키지 않는다.	예방 조치 없음	8	검출 조치 없음	7	504

S x O x D = 9 x 8 x 7 = 504

- S 값이 2개 이상인 경우, 가장 높은 값을 선택하여 RPN 자동 계산

5단계 : Risk Analysis > Risk Matrix

통계 편집기 (Statistics Editor): 리스크 매트릭스 (Risk matrix)											
리스크 매트릭스 (Risk matrix)											
10					1	2					리스크 매트릭스 (Risk matrix) 마지막 조치 상태 (Last revision state); Risk matrix 원인 (Causes) 69 16 1
9											
8											
7					4	3		7			
6											
5						2					
4					9	11		23			
3					2	5		16			
2											
1								1			
0 (O)	1	2	3	4	5	6	7	8	9	10	

S (S) X (O)	번호 (Number)	FMEA-양식 (FMEA form)	시스템 요인 (System element)	기능 (Function)	오류 기능 (Failure)	오류 결과들 (Effects)	C (C)	오류 원인 (Cause)	RP N (RP N)	예방 조치 (Preventive action)	발견 조치 (Detection action)
(7; 10)	2	플러그	와이어와 핀 사이의 납땜 연결	명시된 기계적 안정성을 가진다.	기계적 안정성이 충분하지 않다.	잡는 힘이 너무 약하다. 케이블과 플러그 사이에 전기 연결이 안 되거나 안전하지 않게 연결된다.		단면이 너무 작거나 부적절한 기계적 핀의 기하학적 구조	700	FEM 시뮬레이션	프로토타입으로 테스트
		신호 케이블	신호 케이블	신호를 수신기에서 제어 장치로 손실없이 전달한다.	신호가 없다.	운전이 통제 되지 않는다.		케이블과 플러그 사이에 전기 연결이 안 되거나 안전하지 않게 연결된다.	700	없음	없음
(7;	3	신호 케이블	신호 케이블	실행 조건과	신호가 없다.	운전이 통제		환경으로부터	(34		현재 알려진

6단계 : Optimization

① 추천 조치 내용이 실행된 조치 칸으로 이동

기능 (Function)	요구사항 (Requirement)	잠재적 고장 (Potential failure)	고장의 잠재적 영향(들) (Potential effect(s) of failure)	S (S)	C (C)	고장의 잠재적 원인(들) (Potential cause(s) of failure)	현재 예방 조치 (Current preventive action)	O (O)	현재 검출 조치 (Current detection action)	D (D)	RPN (RPN)	추천 조치 (Recommended action)	책임자/ 마감일 (R/D)	실행된 조치 (Action taken)	S (S)	O (O)	D (D)	RPN (RPN)				
신호를 수신기에서 제어 장치로 손실없이 전달한다.		1.1.a.2 신호가 정확한 입력값을 나타내지 않는다.	{1 크루즈 컨트롤 - 시스템} [크루즈 컨트롤] 1.a.1 운전 통제가 사상을 벗어난다.	9		{1 크루즈 컨트롤 - 시스템} [케이블] 1.1.1.a.1 주어진 실행 조건에서 전송시 신호 조정이 바뀐다.	예방 조치 없음	8	검출 조치 없음	7	504	D: (D) 현재 알려진 실행 조건에서 전송 시뮬레이션을 한다.	홍, 필동, 연구소, 책임 2017-05-11 수정 단계 (in progress)		9	8	7	(504)				
						{1 크루즈 컨트롤 - 시스템} [케이블] 1.1.1.c.1 환경으로부터 전기적으로 전도체를 격리시키지 않는다.																
						{1 크루즈 컨트롤 - 시스템} [케이블] 1.1.1.e.1 전도체를 환경에서의 방해 신호로부터 보호하지 않는다.																
						{1 크루즈 컨트롤 - 시스템} [플러그] 1.1.1.g.1 케이블과 플러그 사이인																

기능 (Function)	요구사항 (Requirement)	잠재적 고장 (Potential failure)	고장의 잠재적 영향(들) (Potential effect(s) of failure)	S (S)	C (C)	고장의 잠재적 원인(들) (Potential cause(s) of failure)	현재 예방 조치 (Current preventive action)	O (O)	현재 검출 조치 (Current detection action)	D (D)	RPN (RPN)	추천 조치 (Recommended action)	책임자/ 마감일 (R/D)	실행된 조치 (Action taken)	S (S)	O (O)	D (D)	RPN (RPN)			
신호를 수신기에서 제어 장치로 손실없이 전달한다.		1.1.a.2 신호가 정확한 입력값을 나타내지 않는다.	{1 크루즈 컨트롤 - 시스템} [크루즈 컨트롤] 1.a.1 운전 통제가 사상을 벗어난다.	9		{1 크루즈 컨트롤 - 시스템} [케이블] 1.1.1.a.1 주어진 실행 조건에서 전송시 신호 조정이 바뀐다.	예방 조치 없음	8	검출 조치 없음	7	504		홍, 필동, 연구소, 책임 2017-05-11 완료됨 (completed)	D: (D) 현재 알려진 실행 조건에서 전송 시뮬레이션을 한다.	9	8	7	504			
						{1 크루즈 컨트롤 - 시스템} [케이블] 1.1.1.c.1 환경으로부터 전기적으로 전도체를 격리시키지 않는다.															
						{1 크루즈 컨트롤 - 시스템} [케이블] 1.1.1.e.1 전도체를 환경에서의 방해 신호로부터 보호하지 않는다.															
						{1 크루즈 컨트롤 - 시스템} [플러그] 1.1.1.g.1 케이블과 플러그 사이인															

② RPN 괄호 사라짐

6단계 : Optimization > FMEA 양식

The screenshot shows the 'Format' menu with the 'Layout' sub-menu open. The 'Layout' sub-menu includes options like '확대 비율 (Zoom)', '열 너비... (Column widths...)', '정렬... (Sort...)', and '열 이름 보여주기 (Show column names)'. The '열 이름 보여주기' option is checked. Below the menu, a table displays FMEA data for a '신호 케이블' (Signal Cable) system element.

요구사항 (Requirement)	잠재적 고장 모드 (Potential failure)	영향(들) (Potential effect(s) of failure)	원인(들) (Potential cause(s) of failure)	현재 예방 조치 (Current preventive action)	현재 검출 조치 (Current detection action)	RPN	추천 조치 (Recommended action)
신호를 수신기에서 제어 장치로 손실없이 전달한다.	1.1.a.1 신호가 없다.	{1 크루즈 컨트롤 - 시스템} [크루즈 컨트롤] 1.a.2 운전이 통제 되지	7	{1 크루즈 컨트롤 - 시스템} [케이블] 1.1.1.d.1 전도체를 물리적, 화학적 영향으로부터 보호하지 않는다.	없음	7	없음
						10	490

제품명	APIS - IQ FMEA
국적	독일
기본 사상	독일 VDA 4. 미국 AIAG Manual
출시 년도	1992년
강점	ISO 26262 포함
	다국적 기업 사용
약점	한글지원 100%
언어	메뉴 언어: 10개국 작성 언어 : 5개국 FMEA 양식 언어 : 23개국
주요고객	국내 : 현대차, 쌍용차, LG전자, LG화학, 삼성SDI, 모비스, 만도, 케피코 국내 60여개 기업 사용 중 해외 : 1,500개 다국적 기업

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VDA Vol-4 Product & Process FMEA

AIAG (4th edition)

MIL Task 101 / MIL Task 102

Deadline tracking according to VDA

DRBFM forms (Design Review based on Failure Mode)

IEC 61508:2010 (IQ-FMEA PRO / IQ-RM PRO Software)

AS 9145

SAE J1739

ISO 14971

QS 9000 (2nd and 3rd)

VDA 86, 96, & 2006

Fault tree analysis according to DIN

Process flow diagrams & Control Plans (Production)





ISO 26262:2011 (IQ-FMEA PRO / IQ-RM PRO Software)

IEC 62304:2006 (IQ-FMEA PRO / IQ-RM PRO Software)

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EPCOS	MANN+HUMMEL	Vaillant				
GKN Driveline	MIELE	VALEO				
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HOERBIGER	MTU Aero Engines	WEBASTO				
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T Thank you



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